Installation guide

CAN-bus adapter for operating key Dynavin radio functions using existing steering-wheel buttons. Supports multifunction steering wheels, time synchronisation and menu-language synchronisation. Steering-wheel buttons must be fitted in the vehicle.

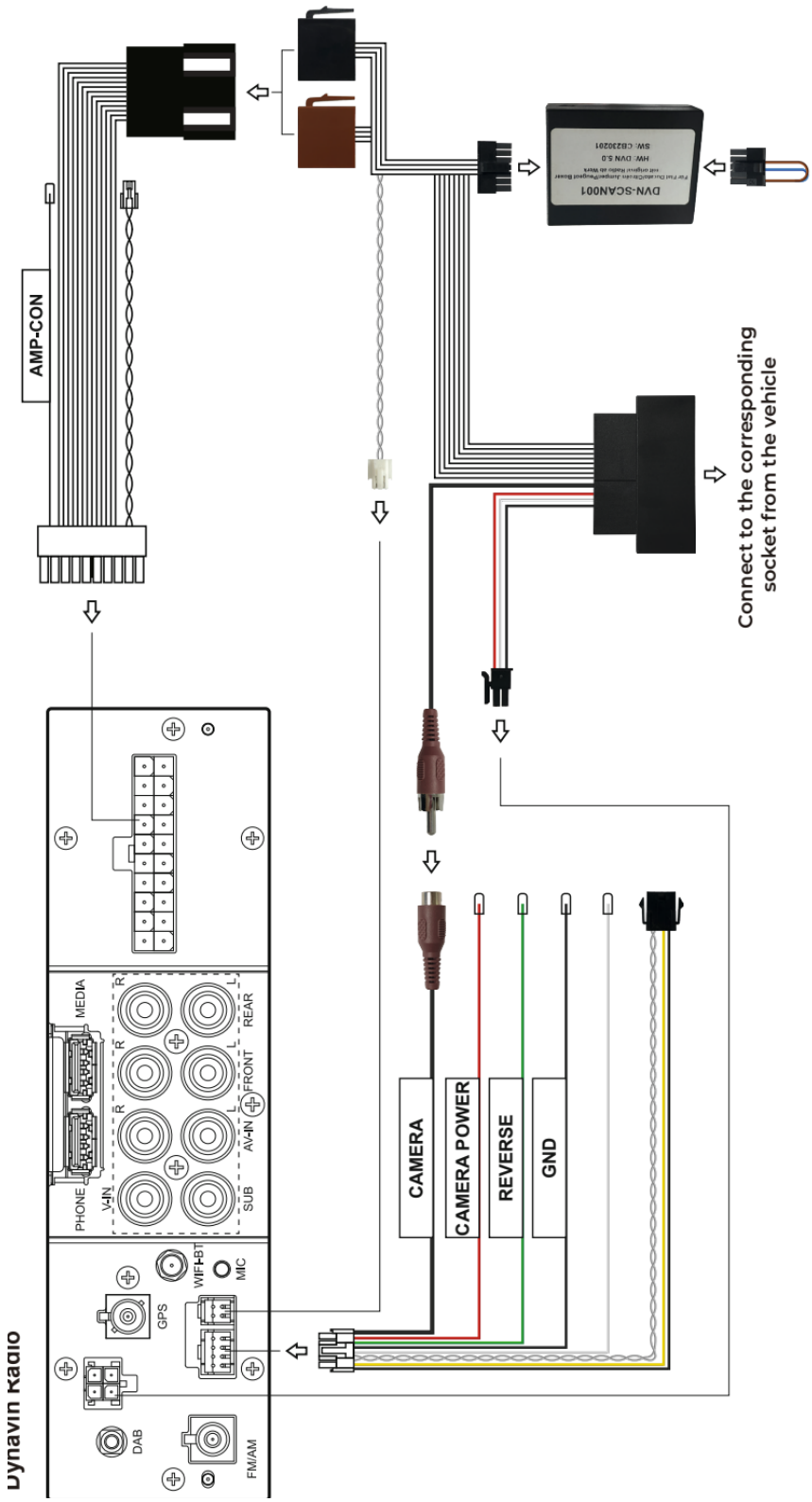
Vehicles listed in the manual: Fiat Ducato III 250/251 (2006–2011), Ducato III EURO 5 250/251 (from 2011), Citroën Jumper II 250/250D/250L (from 2006), Peugeot Boxer II 250/251 (from 2006). For vehicles originally equipped with the factory Fiat radio; compatibility depends on the original radio and connectors.

The next page shows four original-radio examples, from top to bottom: 1) leave empty; 2) positions 1 and 4 connected; 3) positions 1, 2 and 4 connected; 4) positions 1 and 2 connected. Select according to the vehicle’s original radio.

Factory settings can differ from the examples. If an instrument-cluster error remains, the manufacturer instructs checking all illustrated connection options, including leaving the connector empty, until the warning is resolved. A qualified installer should change connections using this guide and the actual harness.

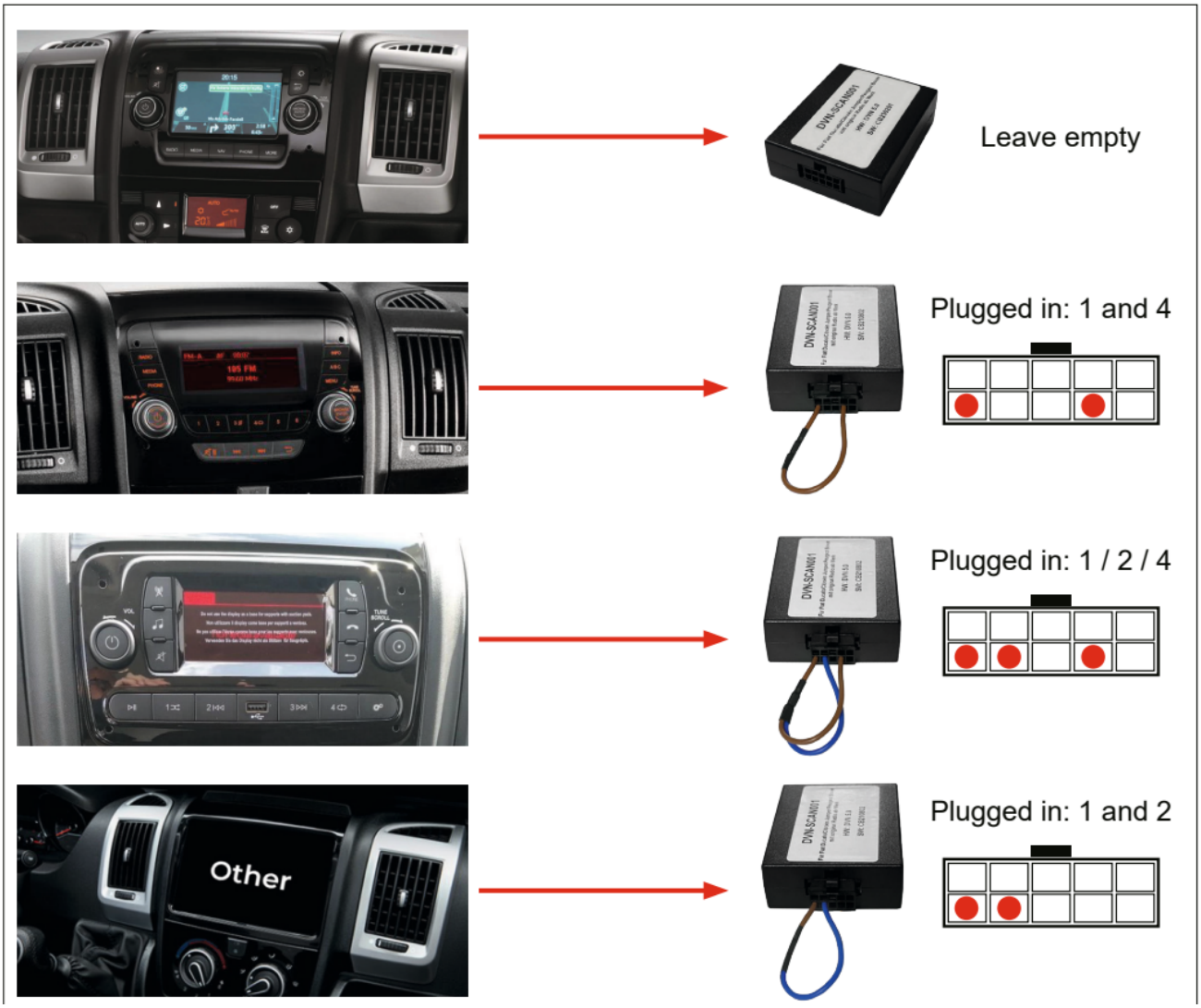
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Dynavin Radio identifies the head unit. Connect to the corresponding socket from the vehicle identifies the vehicle connector. CAMERA is the camera video input; CAMERA POWER is camera power; REVERSE is the reversing signal; GND is ground. Preserve the connector and wire mapping shown in the diagram.

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The illustration shows four original-radio examples, from top to bottom: 1) leave empty; 2) positions 1 and 4 connected; 3) positions 1, 2 and 4 connected; 4) positions 1 and 2 connected. Select according to the vehicle's original radio.

Factory settings can differ from the examples. If an instrument-cluster error remains, the manufacturer instructs checking all illustrated connection options, including leaving the connector empty, until the warning is resolved. A qualified installer should change connections using this guide and the actual harness.